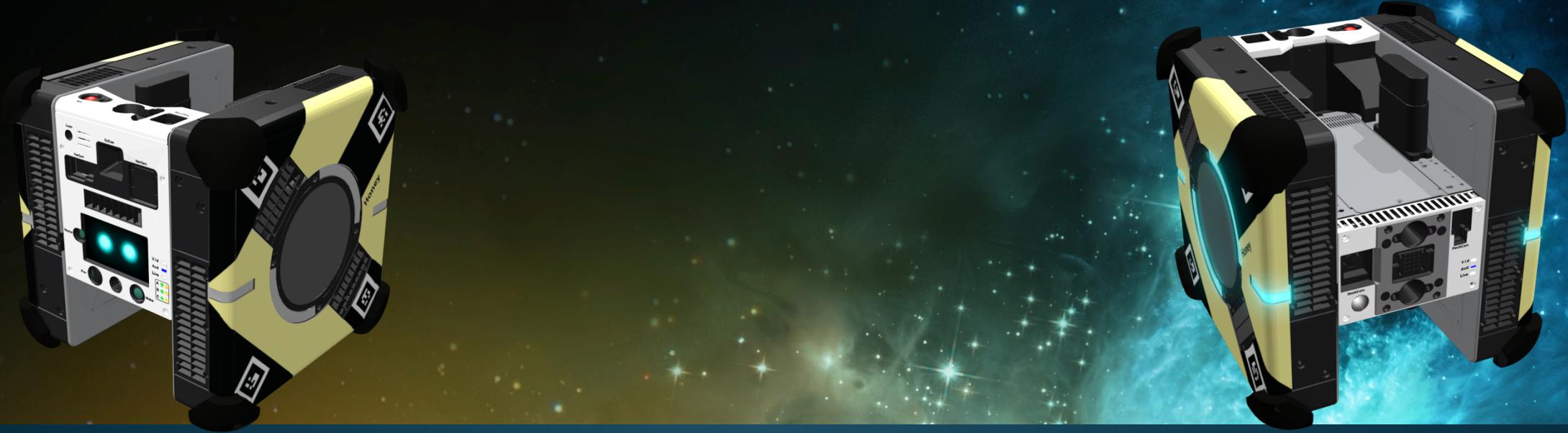




Astrobee: Autonomous free flying robots for the ISS

Roberto Carlino

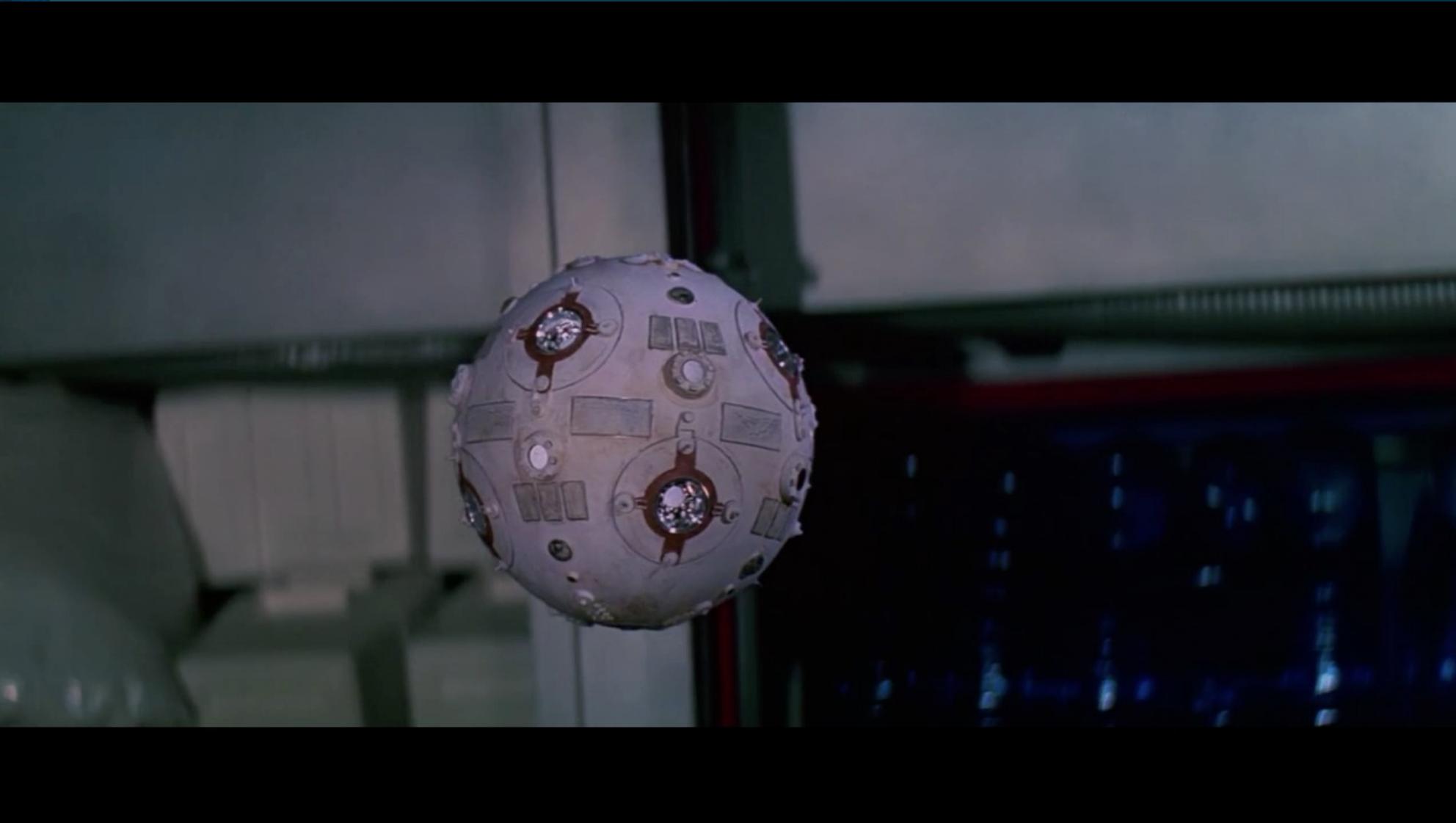


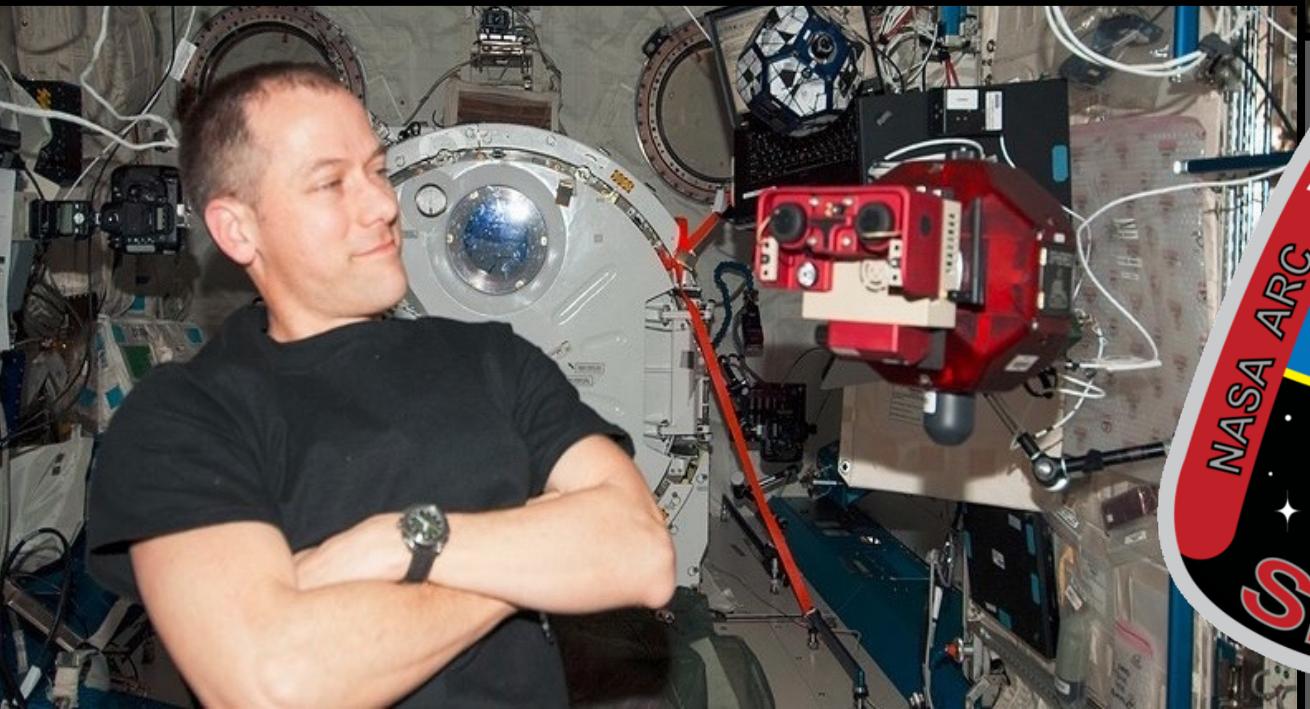
Science Fiction Inspires Real Science



Science Fiction Inspires Real Science

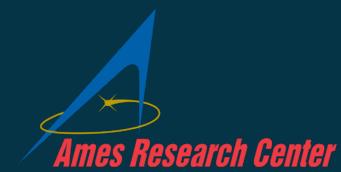
JPL Research Center





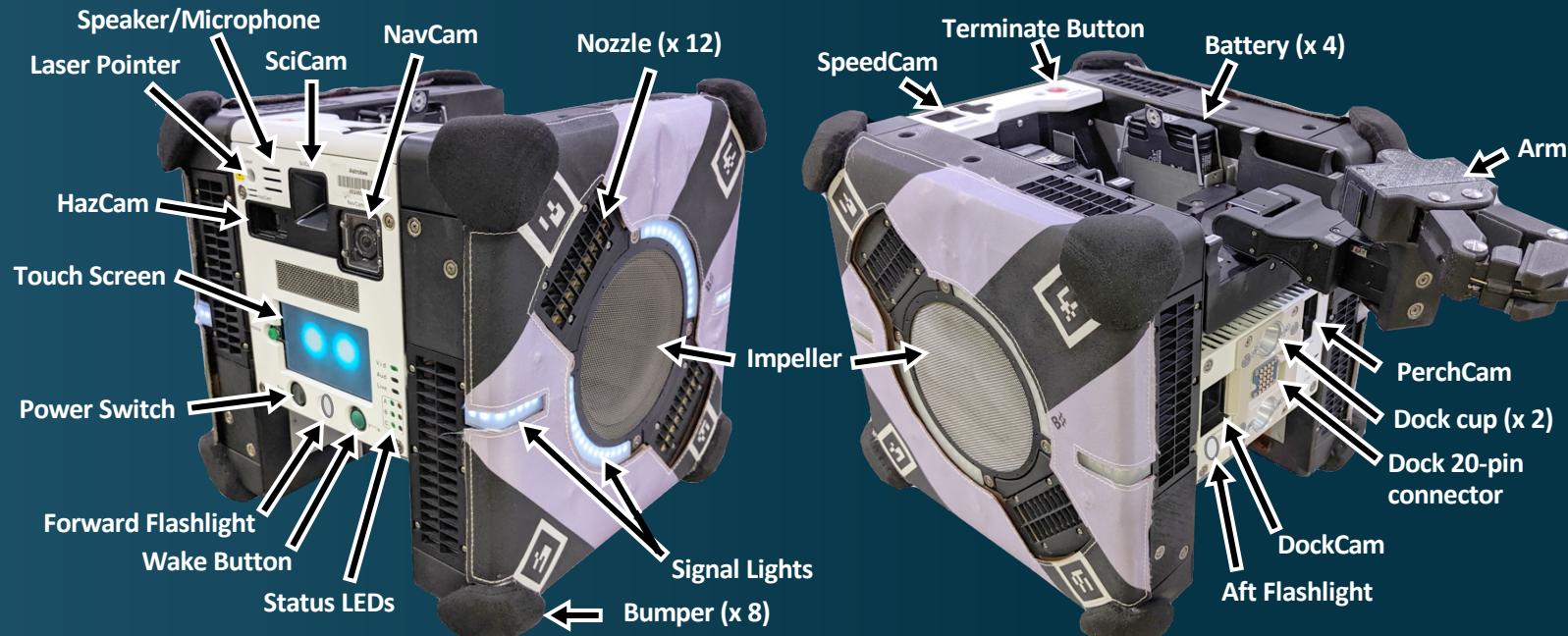
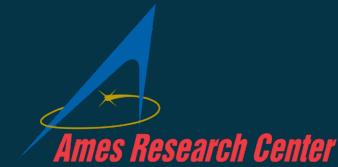


Astrobee on the ISS





Astrobee free flyer

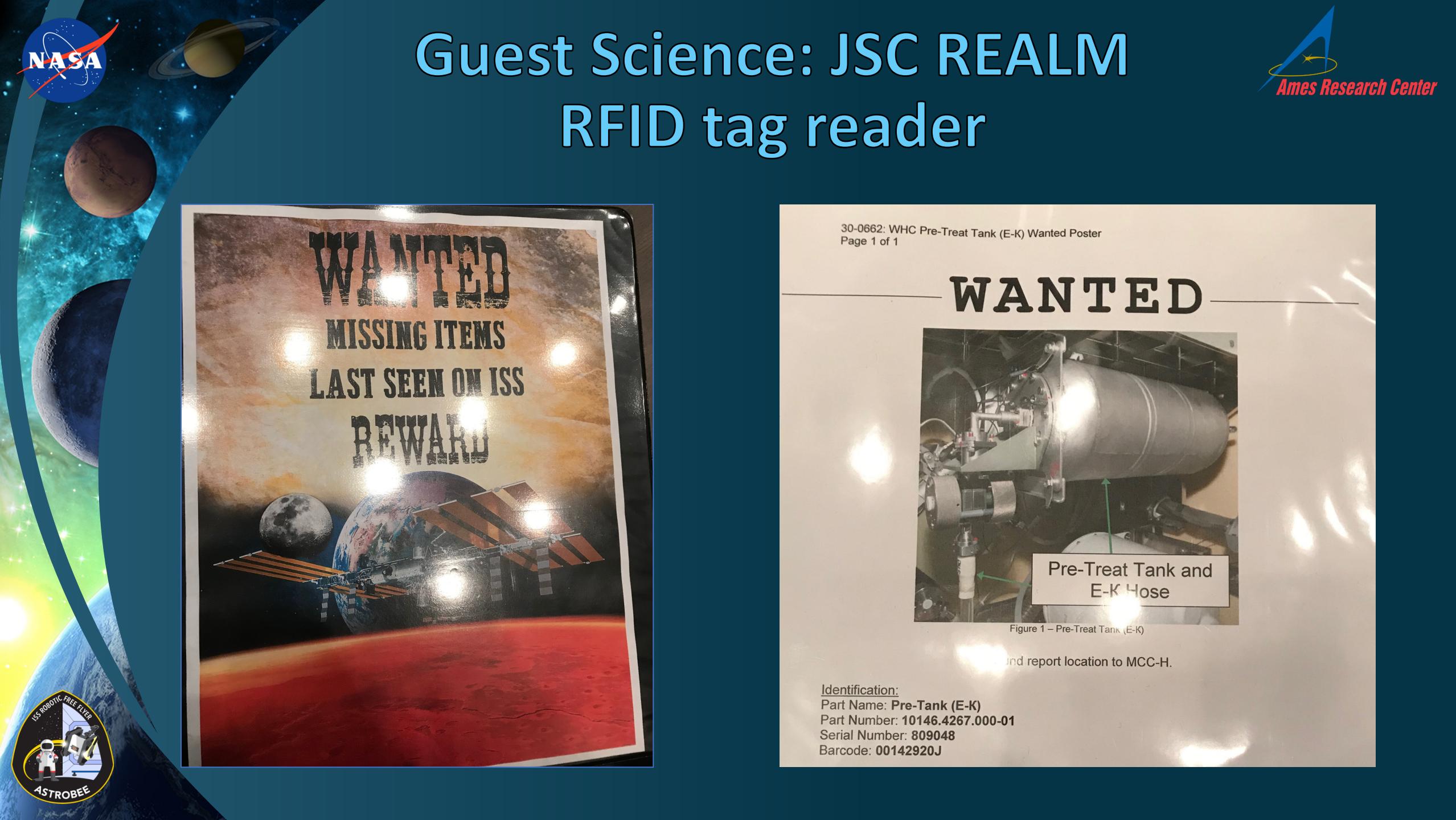


- 1 Provide a microgravity robotic research facility in the ISS, which will replace the existing SPHERES facility
- 2 Provide remotely operated mobile camera views of the ISS to enhance the situation awareness of mission control
- 3 Perform mobile sensor tasks in the ISS

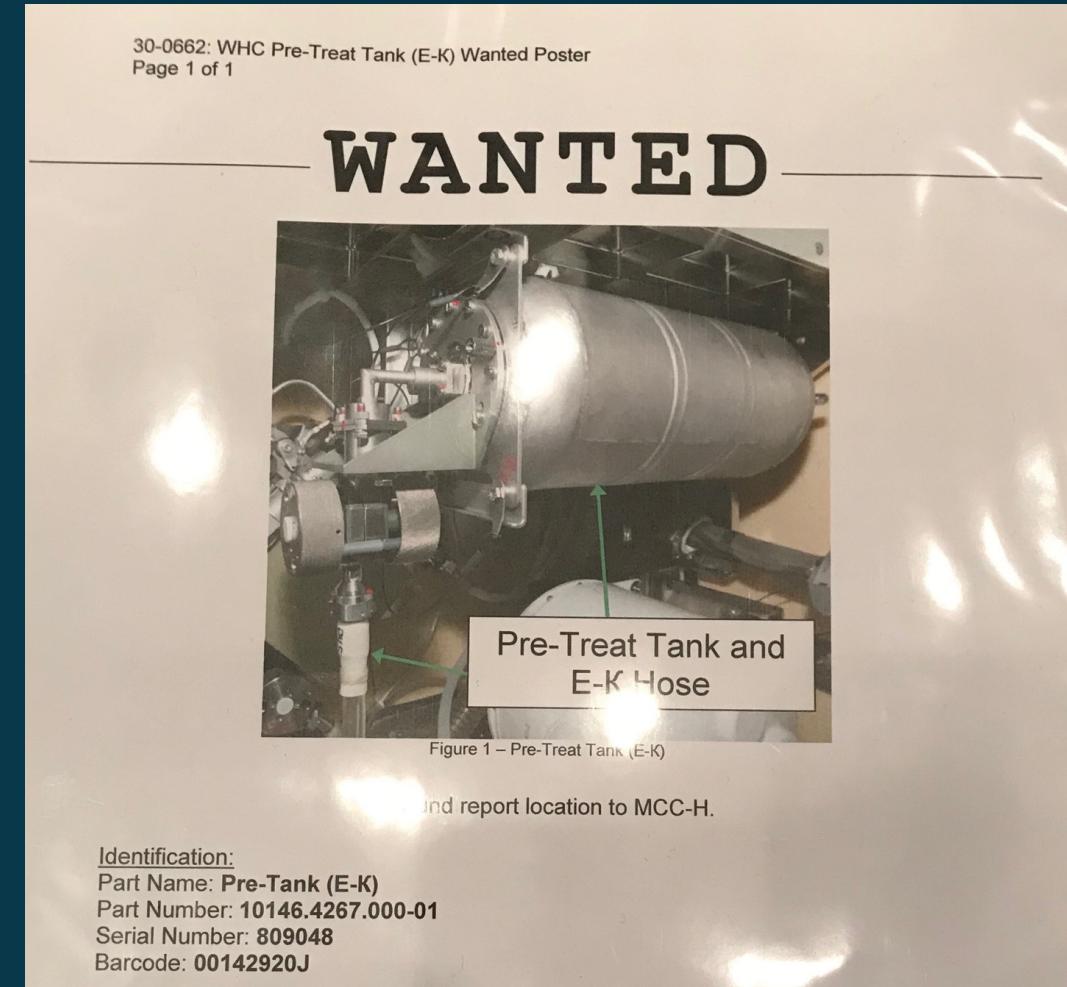




Astrobee Guest Science Payloads

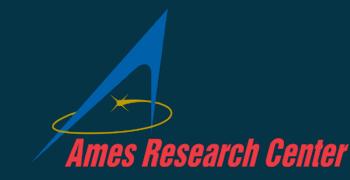


Guest Science: JSC REALM RFID tag reader

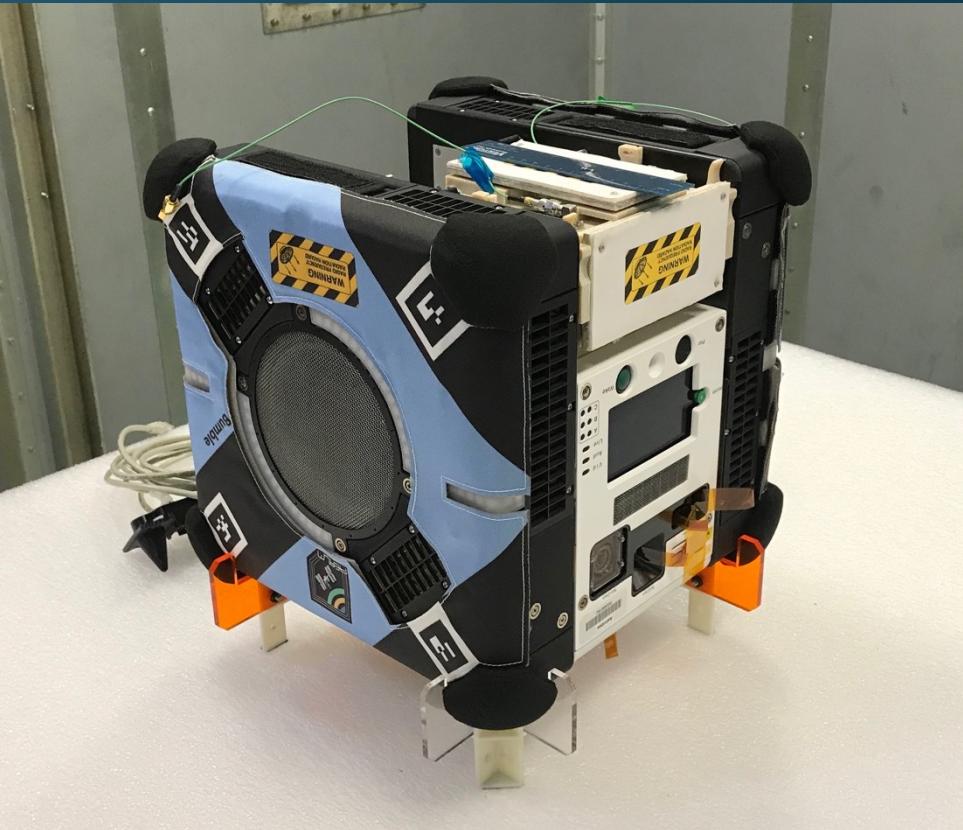




Guest Science: JSC REALM RFID tag reader



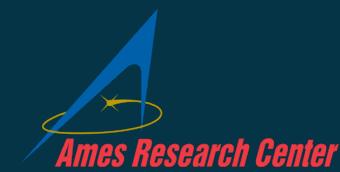
- RFID reader allows inventory and searches for logistics reduction
- Launching on NG-12



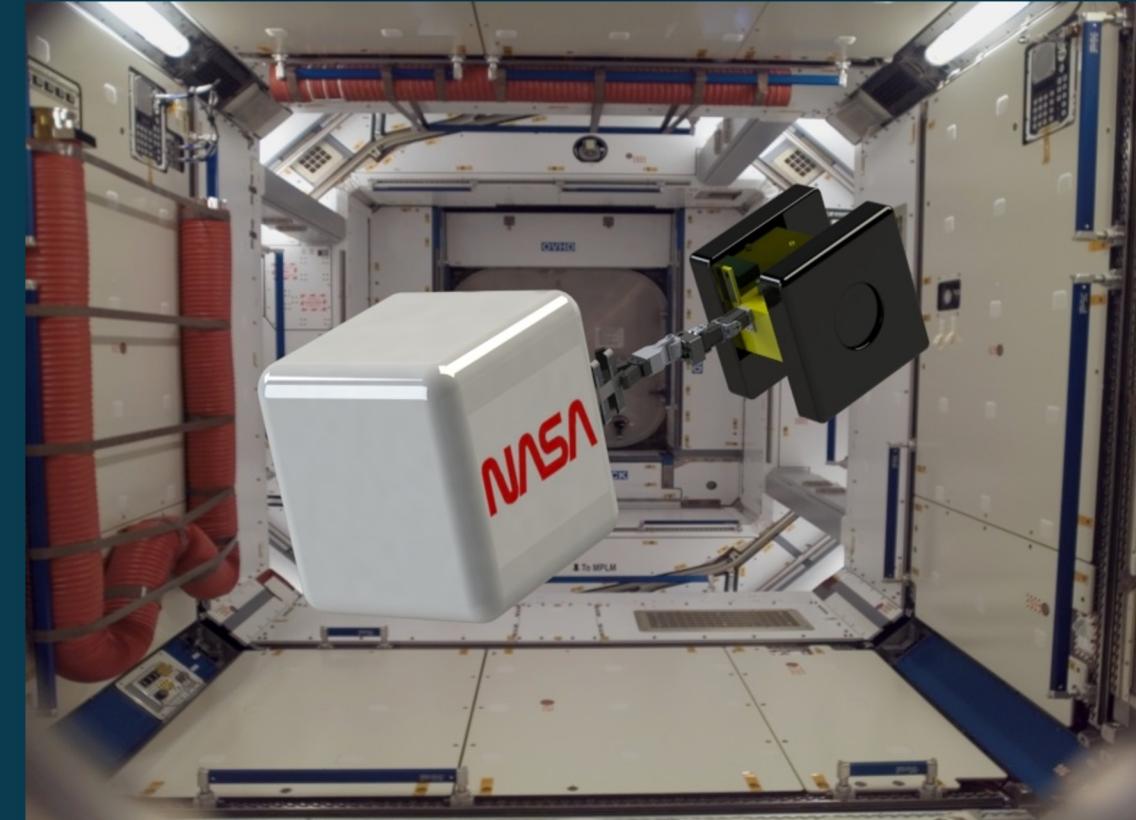
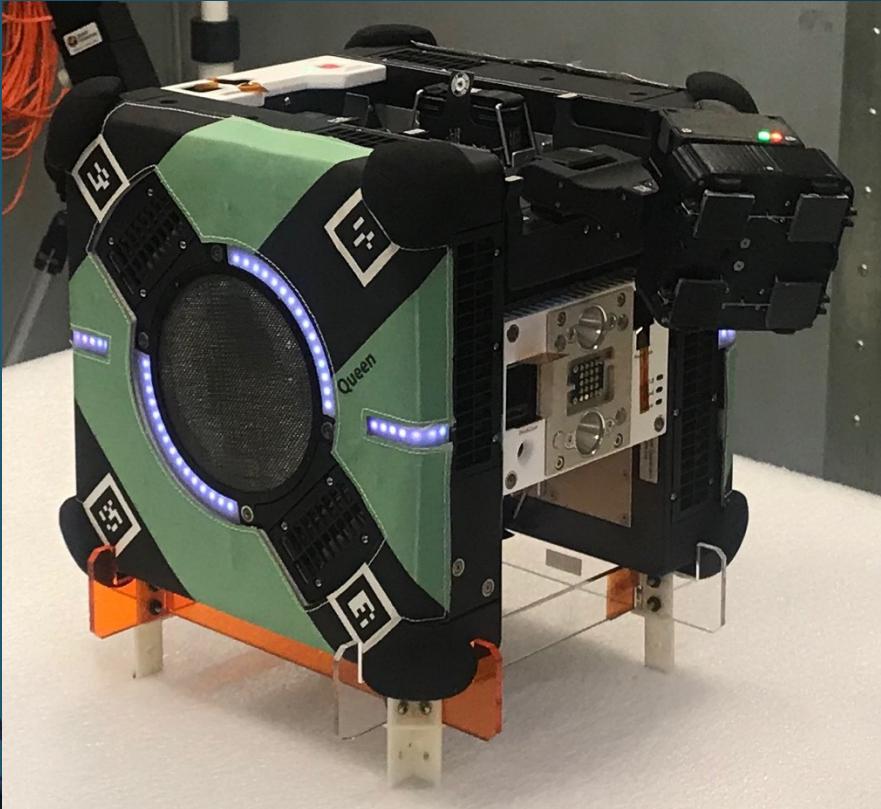
Credit: NASA JSC



Guest Science: Stanford Gecko Adhesive Gripper

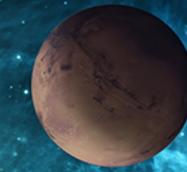


- Gecko-inspired end-effector for gripping of smooth surfaces
- Launched in 2019

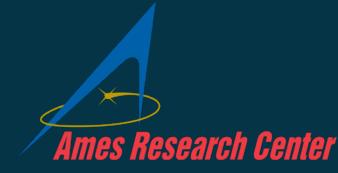


Credit: Stanford

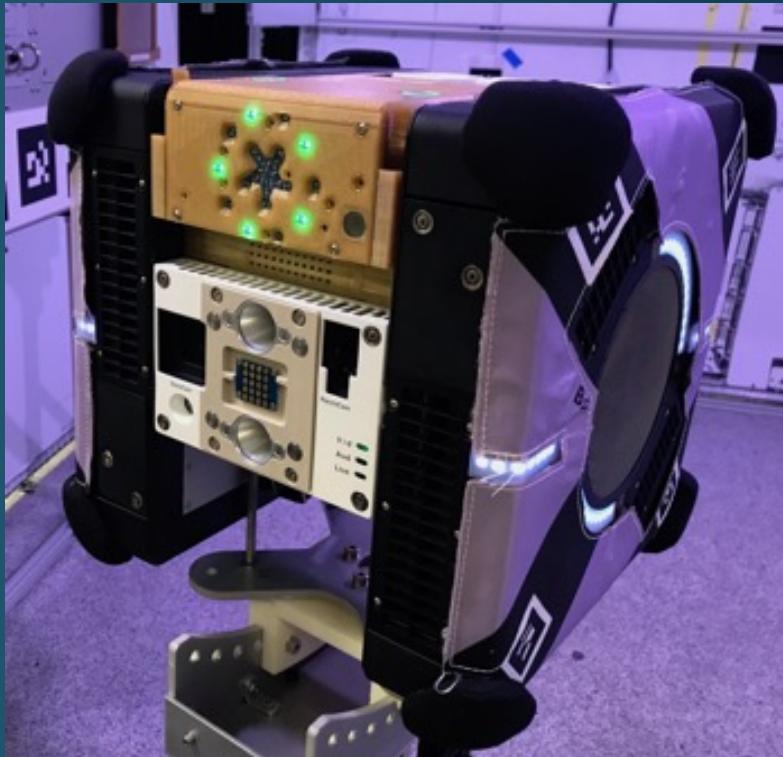




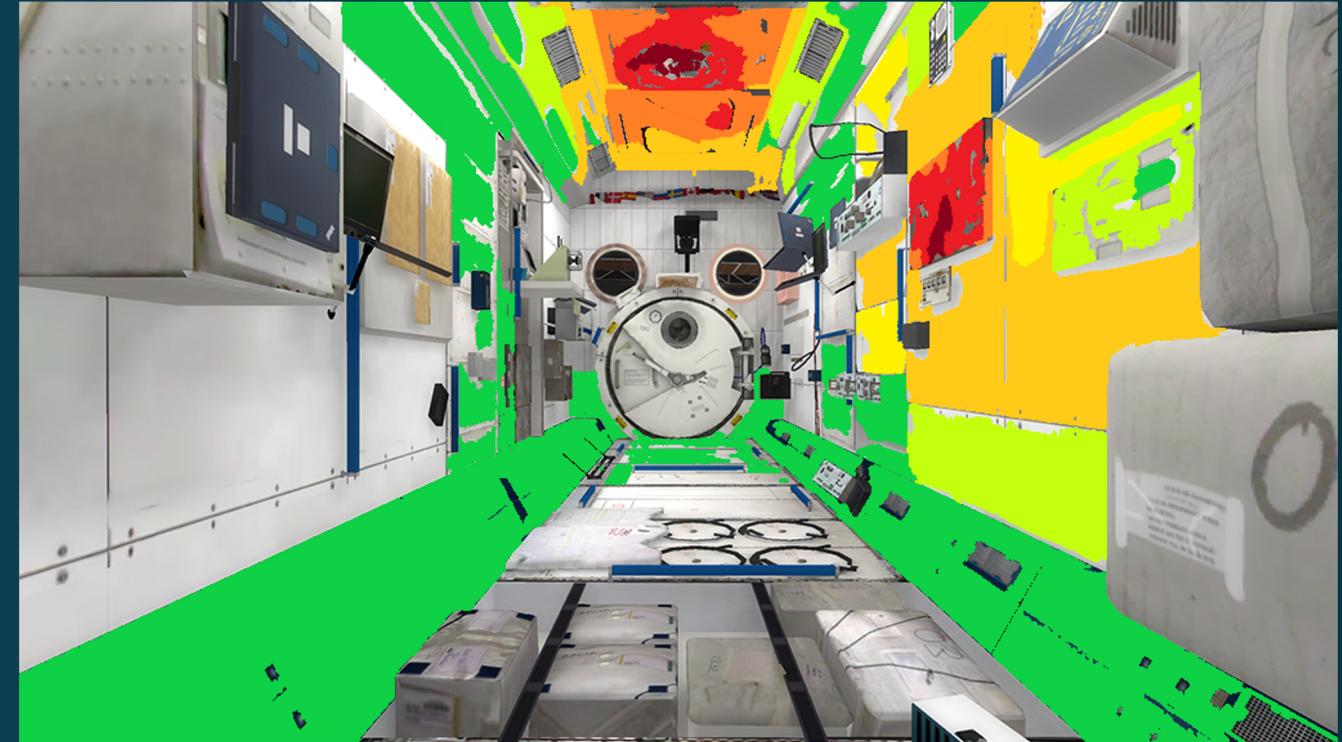
Guest Science: Astrobotic SoundSee



- Microphone array that creates a sound map used to monitor health of on-board systems
- Launched in 2019



SoundSee payload



Heat maps

Credit: Astrobotic/BOSCH



Astrobee Status

Fleet of AstroBees



Dock Station and 3 Astrobees onboard the ISS.

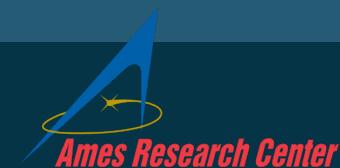
- **Bumble**
- **Honey** (down for repair)
- **Queen**



Bsharp and WannaBee
at NASA Ames.



ISaac Camera survey



Integrated System for Autonomous and Adaptive Caretaking (ISaac)

Survey Demo

Abiola Akanni, Oleg Alexandrov, Laura Barron, J Benton,
Maria Bualat, Brian Coltin, Janette Garcia, Kathryn
Hamilton, Lewis Hill, Marina Moreira, Robert Morris, Nicole
Ortega, Joseph Pea, Misha Savchenko, Khaled Sharif, Trey
Smith, Ryan Soussan

June 2021



Future tasks

Astrobee will help prove out the concept of “Caretaker Robots” for future Intra-Vehicular Robotic (IVR) exploration (Lunar Gateway).

Monitor the environment

- Ensure crew health and safety

- Maintain vehicle health and longevity

- Sound levels, radiation, air quality

Inspection functions can include:

- Spot checks

- Surveys (RFID localization)

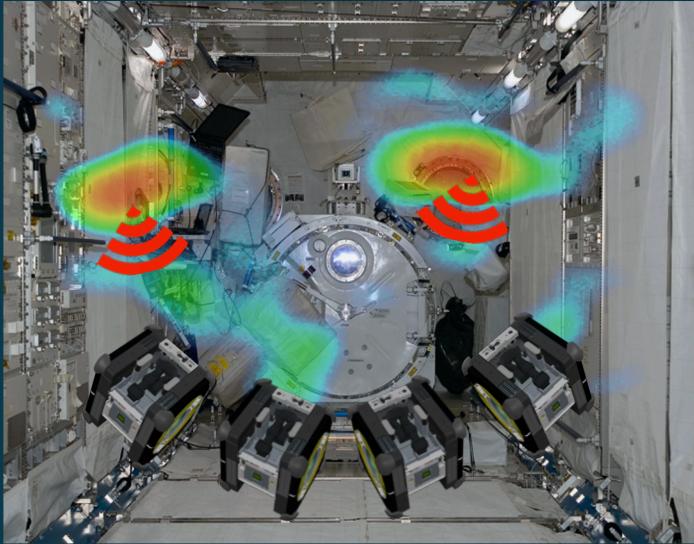
- Localizing problems

With dexterous robotic manipulation, future tasks could include:

- Maintenance

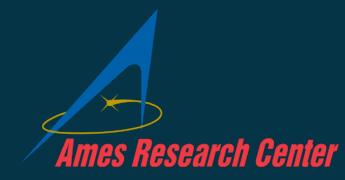
- Repair

- Cargo transfer





NASA Astrobee Game





Zero Robotics student competition



Conclusions

Astrobee will allow guest scientists to test new technologies on the ISS

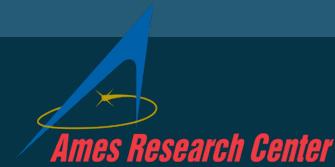
Improves crew safety, by monitoring the environment

A lot of uses and tasks to help astronauts (essential for future long term Space Exploration)

Currently **Bumble and Queen** on the ISS.

Dozens of guest science ISS experiments in progress





Thanks very much for the attention!



Fun
with
Robots



Any questions?

